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(71) Applicant(s)

International Mobile Satellite Organization
99 City Road, LONDON, EC1Y 1AX, United Kingdom(56) Documents Cited
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(72) Inventor(s)

George V Kinal
James R Nagle 11
Claudio Soddu
Fintan R Ryan(58) Field of Search
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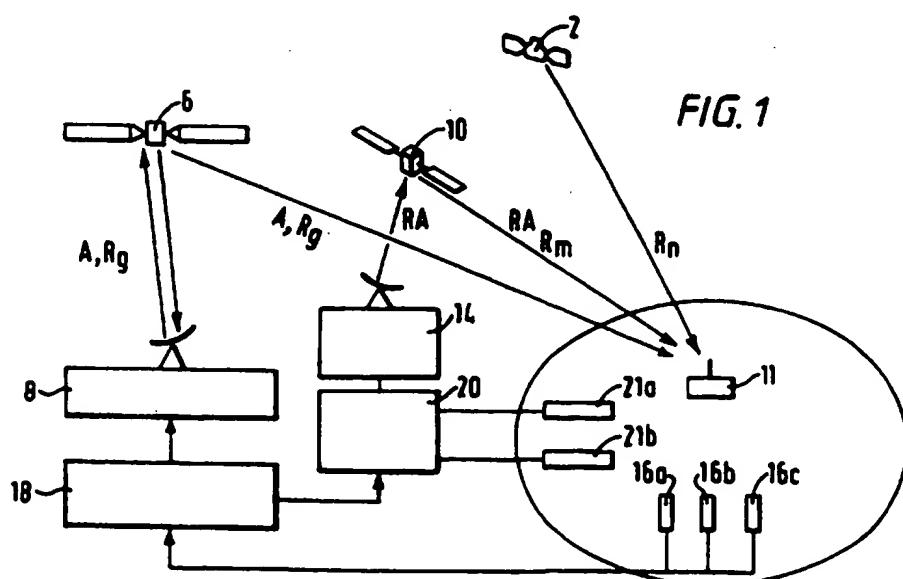
(74) Agent and/or Address for Service

R G C Jenkins & Co
26 Caxton Street, LONDON, SW1H 0RJ,
United Kingdom

(54) Satellite radiodetermination

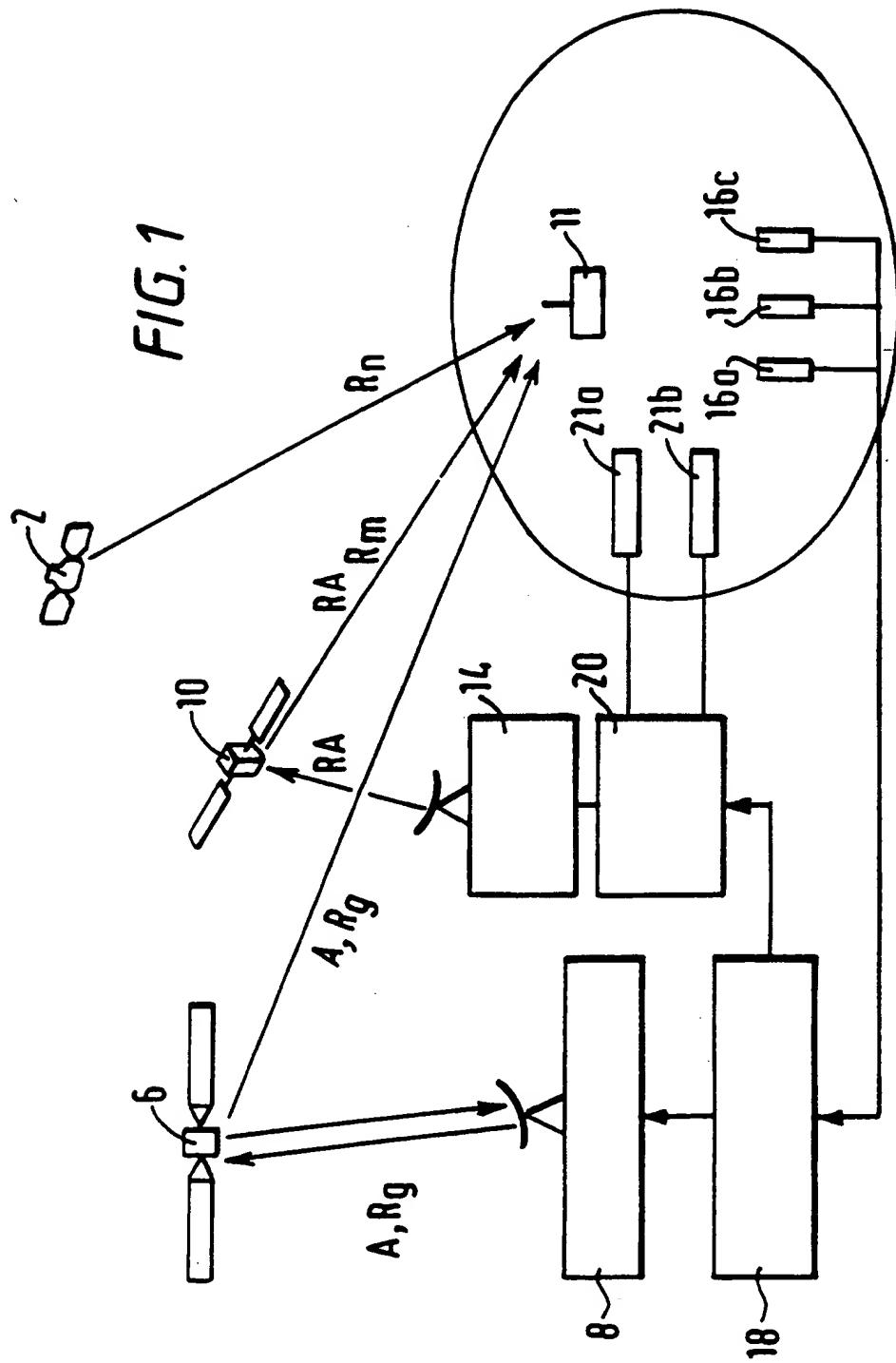
(57) A satellite radiodetermination system comprises global navigation service (GNSS) satellites 2 such as GPS satellites, which generate GNSS ranging signals R_g , geostationary satellites 6 which retransmit ranging signals R_g generated at a navigation land earth station (NLES) 8, including augmentation data A indicating ionospheric delays, selective availability degradations, etc., and medium earth orbit (MEO) satellites 10 which generate GPS-type ranging signals R_m including regional augmentation data RA transmitted from a satellite access node (SAN) 14. The regional augmentation data RA is supplied by regional augmentation systems 21a, 21b.

A navigation receiver 11 receives the ranging signals R_g , R_m , R_n and calculates ionospheric delay values for those ranging signals which are provided on dual frequencies. Using these ionospheric delay values, and optionally the regional augmentation data RA and the augmentation data A, the navigation receiver estimates ionospheric delay values for those ranging signals which are provided on single frequencies. The navigation receiver uses the ranging signals, corrected for ionospheric delay and errors indicated by the augmentation data A and regional augmentation data RA, to calculate position and time accurately.



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FIG. 1



23 10 96

216

FIG. 2

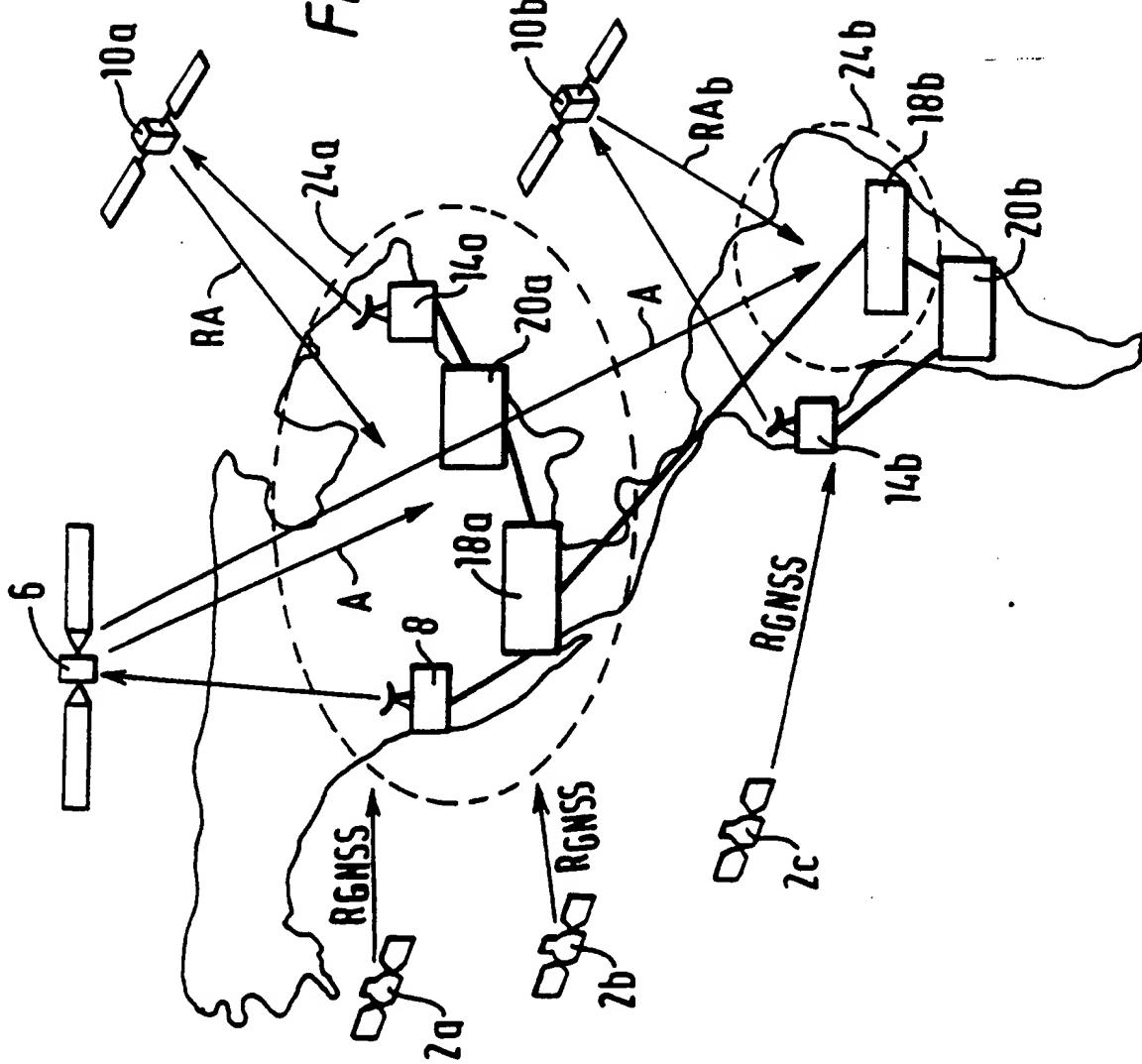
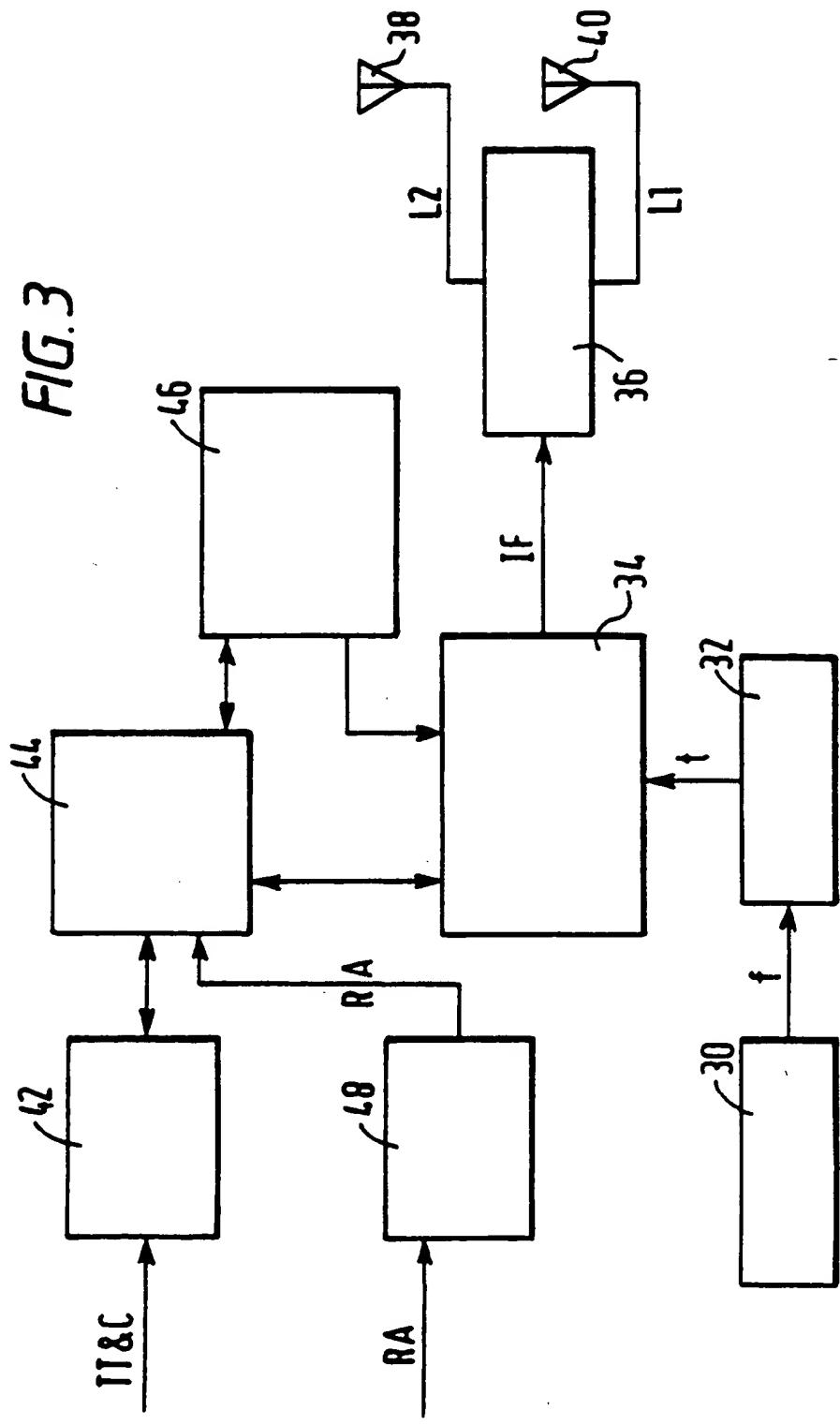
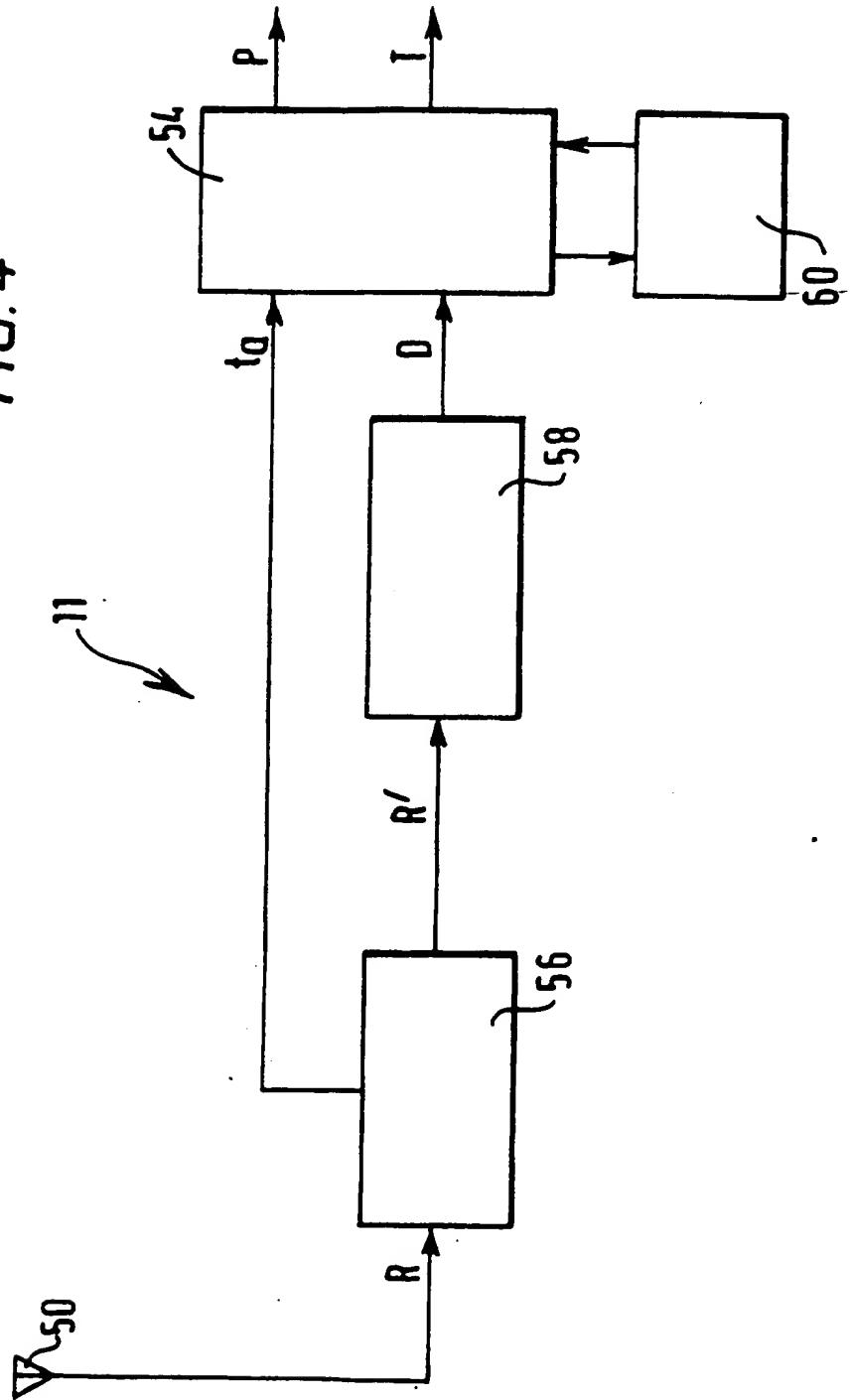


FIG. 3



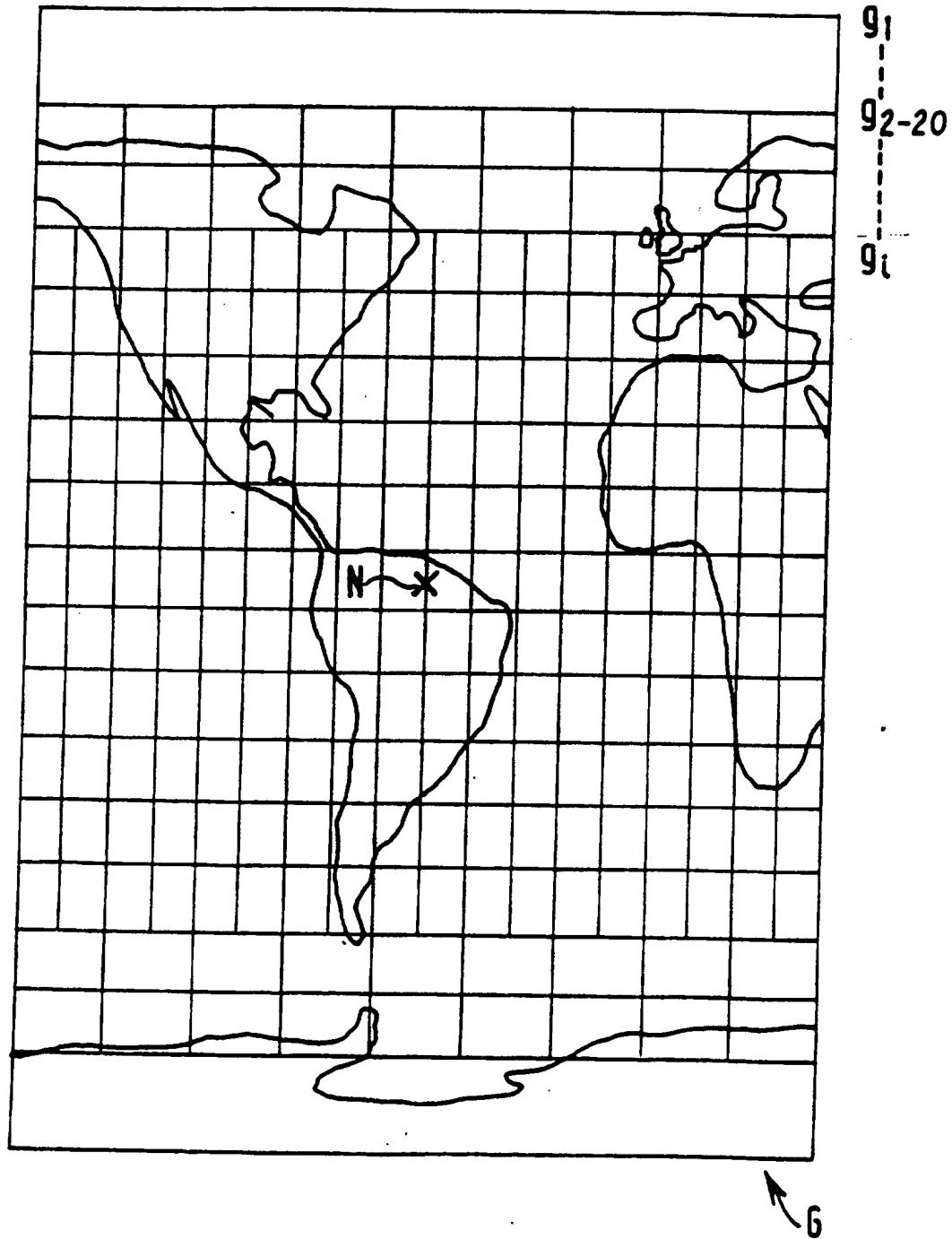
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FIG. 4

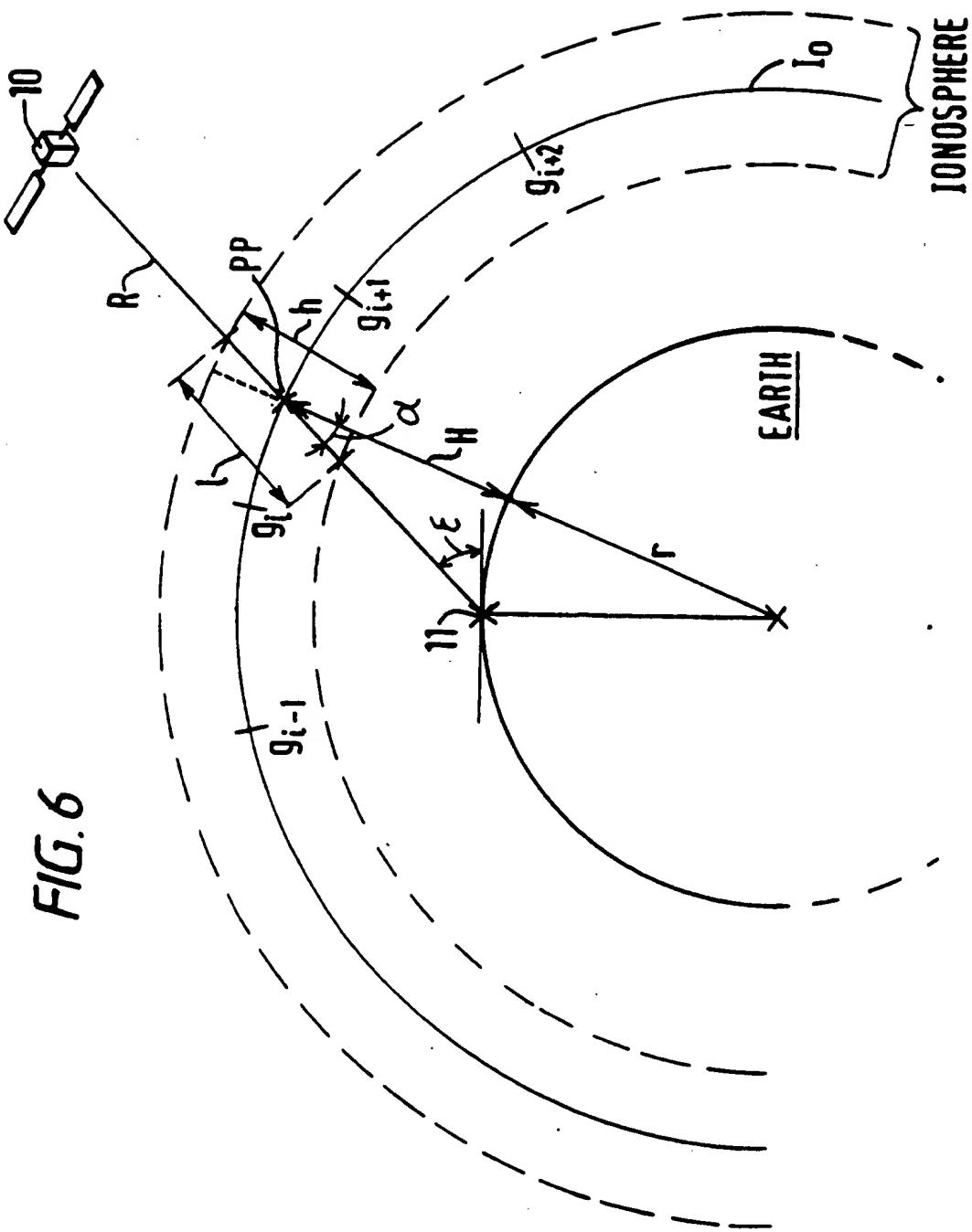


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FIG. 5



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SATELLITE RADIODETERMINATION

This invention relates to methods and apparatus for radiodetermination. Radiodetermination comprises the determination of position and/or time by the use of ranging signals between a terminal and a plurality of beacons. In satellite radiodetermination the beacons are satellites in orbit.

At the present time, two global radiodetermination systems exist. The GPS/NAVSTAR system comprises a constellation of satellites in twelve hour orbits, operated by and for the US Department of Defense. The GLONASS positioning system provides similar facilities under the control of the Russian government (and will not be discussed further herein).

In the GPS/NAVSTAR system, each satellite carries a highly accurate atomic clock and the clocks of all the satellites are synchronised. The orbits of all the satellites are well characterised, and each satellite is therefore able to derive its instantaneous position. The satellites periodically receive information on variations in their orbits from a terrestrial station.

The satellites broadcast regular messages which carry:

1. the time, as indicated by the on-board atomic

clock,

2. the position of the satellite, and
3. status messages.

5 Details of the GPS signal format may be found in the "Global Positioning System Standard Position Service Signal Specification", 2nd edition, 2 June 1995, incorporated herein by reference.

10 A GPS receiver on earth is able to acquire signals from several satellites. The constellation is designed so that, for almost every point on earth at almost every time of day, at least four satellites are simultaneously in view. By noting the different times of arrival of signals from different satellites, using the received clock data, and with knowledge of the 15 satellite positions (transmitted with the signals), the GPS receiver is able to calculate the relative range from each satellite and, from these four relative ranges thus calculated, to calculate its position in three dimensions and calibrate its clock.

20 Changes in the delay caused by variations in the ionosphere can degrade the accuracy of radiodetermination measurements, and accordingly, to enable some compensation for this, each satellite broadcasts on two frequencies (termed L1 and L2). A 25 military GPS receiver is able, by measuring on two frequencies, to estimate and correct the ionospheric delay, since the ionospheric delay varies as a

function of frequency.

Although GPS/Navstar is primarily for military use, receivers are widely available to civilians. However, the civilian receivers cannot decode the "P-code" by which information signals are encrypted on the first and second frequencies and hence cannot perform a two-frequency ionospheric compensation. Also, to limit the accuracy of the service to non military users, the so called "selective availability" feature introduces deliberate minor errors of timing and/or position into the information signals encoded by the "C/A code" and transmitted only on the L1 frequency from various satellites. Military receivers are able to decode signals without these deliberate errors.

It is possible for a ground station of accurately known position to determine which satellites are in error and by how much, and it is known to broadcast a signal which indicates which satellites are in error, and the amount of correction to apply for reception by GPS receivers, to enable them to compensate the errors from a single frequency measurement and thus derive a reliable position signal. Broadcasting such signals via a geostationary satellite is taught in, for example, US 4445110.

However, whilst the correction to be applied can be calculated exactly by the reference ground station

of known position, this correction becomes progressively less accurate further away from the reference ground station, because of differences in the ionosphere (and other layers of the atmosphere such as the troposphere). Accordingly, the usefulness 5 of such "differential GPS" techniques is limited.

Rather than providing a GPS receiver which operates to receive two frequencies in order to compensate for ionospheric variations, or one which 10 receives a differential GPS correction, it is possible to broadcast a signal which includes some data about ionospheric conditions. In recent years, the possibility of a wide area differential system has been discussed. One example is the Wide Area 15 Augmentation System (WAAS) proposed by the US Federal Aviation Authority to provide differential correction information over the US. In such a wide area system, ionosphere correction data for a grid of spaced apart points in an area (e.g. Europe or the US) is broadcast 20 via a geostationary satellite serving that area, and at the receiver, an interpolation is performed between grid points to derive a value for the ionosphere delay correction to be applied to a single frequency signal from each GPS satellite in view. Also broadcast is 25 correction data for compensating for "selective availability" errors. US-A-5323322 describes a satellite radiodetermination system in which

ionosphere data is broadcast.

It has been proposed in the papers "Evolution to civil GNSS taking advantage of geostationary satellites", ION 49th Annual Meeting, June 1993, 5 "Implementation of the GNSS integrity channel and future GNSS growth considerations", INA 18th Annual Meeting, October 1993, and "Global Navigation Satellite System (GNSS) Alternatives for Future Civil Requirements", PLANS '94 Technical Program, April 10 1994, all by J.R. Nagle, G.V. Kinal and A.J. Van Dierendonck, to supplement the GPS/NAVSTAR system by additional civil satellites in low earth, intermediate or geostationary orbits.

According to one aspect of the present invention, 15 there is provided a satellite radiodetermination receiver which receives a multiple frequency ranging signal and a single frequency ranging signals, derives an ionospheric delay value from the multiple frequency ranging signal by measuring the relative delay between the different frequencies at which the multiple frequency ranging signal is transmitted and estimates 20 a delay value for the further ranging signal on the basis of the measured ionospheric delay value for the multiple frequency ranging signal.

According to another aspect of the present 25 invention, there is provided a satellite payload which is operable in either one of two modes. In the first

mode, the satellite payload generates autonomous ranging signals which do not include augmentation data received from a ground station. In the second mode, the satellite additionally relays augmentation data received from the ground station.

In another aspect of the present invention, there is provided a satellite payload which is able to generate an autonomous ranging signal and to broadcast data received from a ground station. If no data is received from the ground station, the satellite payload generates dummy data for broadcast, so as to keep the broadcast channel open.

According to another aspect of the present invention, there is provided a satellite radiodetermination receiver which receives augmentation data including an indication of the origin or applicability of the augmentation data. The receiver selects portions of the augmentation data for performing radiodetermination on the basis of the indication of applicability or origin.

According to another aspect of the present invention, there is provided apparatus for connection to a satellite access node, which is arranged to receive augmentation data, to determine the position of a satellite accessible by the satellite access node, to determine whether the position of the satellite falls within a predetermined range dependent

on the source of the augmentation data and to output augmentation data to the satellite access node if the position of the satellite falls within the predetermined range.

5 According to another aspect of the present invention, there is provided a satellite navigation receiver which is able to receive ionospheric delay data but is only able to use the ionospheric delay data when performing radiodetermination if access to
10 the ionospheric delay data is enabled, for example by means of a code for decrypting the ionospheric delay data.

According to a further aspect of the present invention, there is provided an apparatus for
15 providing augmentation data to a satellite access node which is arranged to encrypt ionospheric delay data without encrypting differential correction data which does not relate to ionospheric delay and to output the encrypted ionospheric delay data and the unencrypted differential correction data to the satellite access
20 node.

According to another aspect of the present invention, there is provided a satellite navigation receiver which is arranged to receive ionospheric delay data and residual error data and to correct the ionospheric delay data using the residual error data.
25

According to another aspect of the present

invention, there is provided a differential correction network which receive ionospheric delay data from another differential correction network, receives ranging signals from navigation satellites and thereby 5 calculates errors in the ionospheric delay data.

Embodiments of the invention will now be illustrated, by way of example only, with reference to the accompanying drawings in which:

Figure 1 is a schematic diagram of a satellite 10 radiodetermination system;

Figure 2 is a schematic diagram of a portion of the satellite radiodetermination system serving North and South America;

Figure 3 is a block diagram of the navigation 15 payload of a MEO satellite;

Figure 4 is a block diagram of a navigation receiver;

Figure 5 is a diagram of a grid used to represent 20 ionospheric information; and

Figure 6 is a diagram to illustrate calculation 25 of ionospheric pierce points.

Navigation System

Figure 1 shows schematically the elements of a satellite radiodetermination system and the 25 relationship between them. Autonomous ranging signals R_n are provided by one or more GNSS (Global Navigation Satellite Service) satellites 2, such as GPS Navstar

satellites and/or GLONASS satellites. A plurality of geostationary satellites 6, such as the proposed Inmarsat-3 communications satellites or dedicated geostationary navigation satellites, each carry a 5 navigation transponder for relaying differential correction and other augmentation data A from a navigation land earth station (NLES) 8 to navigation receivers 11, the augmentation data A providing integrity, error and ionosphere information relating 10 to the GNSS satellites 2 and their ranging signals R_n .

One or more medium earth orbit (MEO) satellites 10, such as the proposed satellites for the I-CO (TM) global satellite communications system, relay regional augmentation data RA transmitted by a terrestrial 15 satellite access node (SAN) 14 to the navigation receivers 11 incorporated in autonomous ranging signals R_m synchronised with the ranging signals R_n from the GNSS satellites 2. The proposed satellites for the I-CO (TM) system are a constellation of ten 20 satellites in 6 hour orbits in two orbital planes, each carrying a communications and navigation payload.

A network of monitoring stations 16a, 16b and 16c, of accurately known location, receive the ranging signals R_n from the GNSS satellites 2, and the ranging signals R_m from the MEO satellites 10 and calculate 25 errors in the position and time information contained in these ranging signals from the difference between

the positions calculated from the ranging signals R and the actual positions of the monitoring stations 16. Differential correction data is transmitted from the monitoring stations 16a, 16b and 16c to a regional control station 18 which derives the augmentation data A, including errors in the reported positions and time signals of the MEO satellites 10, and of the GNSS satellites 2. The monitoring stations 16 may alternatively be simple receivers with the calculation of differential correction being performed at the regional control station 18.

The position and timing errors in the ranging signals R do not vary between the monitoring stations 16a, 16b and 16c. However, the differential correction data received from the monitoring stations 16a, 16b and 16c will differ because of the difference in ionospheric delay in the signals received by each of the monitoring stations 16, dependent on the quantity of free electrons in the parts of the ionosphere through which the signals travel, together with other delays such as tropospheric delays caused by tropospheric refraction.

Therefore, the regional control station 18 is able to derive separately data for errors in the ranging signals R, R_a and for values of ionospheric delay in the region of the ionosphere through which the ranging signals travel to reach each of the

monitoring stations 16a, 16b and 16c. This data is transmitted to the NLES 8 for transmission as the augmentation data A via the geostationary satellites 6 to the navigation receivers 11.

5 Additionally, the augmentation data is transmitted to a service network 20 accessible by providers of regional augmentation systems 21a, 21b. Such regional augmentation systems 21a, 21b may include local monitoring stations for calculating
10 differential correction data for specific regions. Regional augmentation data RA, which may for example include more accurate ionospheric data and corrections to the augmentation data A relevant to the specific regions, is input by the service providers at the
15 service network 20. The regional augmentation data RA may include some or all of the augmentation data A. The regional augmentation data RA is transmitted to the SAN 14 for transmission via the MEO satellites 10 and selective reception by the navigation receivers
20 11.

25 The satellite radiodetermination system described above provides, in addition to existing satellite radiodetermination services such as GPS and GLONASS, the additional ranging signals R from the MEO satellites 10. In this embodiment, the ranging signals R are dual-frequency ranging signals similar to the signals available to military users in the GPS

system, but are unencrypted and therefore available to any user. The above radiodetermination system also broadcasts augmentation data A over a wide area via the geostationary satellites 6, which is supplemented 5 by additional regional augmentation data RA broadcast by the MEO satellites 10.

The augmentation data A is encoded in ranging signals R_g generated by the NLES 8 and broadcast via the geostationary satellite 6 to the navigation receivers 11. The location of the geostationary satellite 6 is determined at the NLES 8, which also includes an accurate time reference, such as an atomic clock or a dual frequency satellite radiodetermination apparatus, synchronised to those on board the MEO satellites 10 and the GNSS satellites 2. The delay 10 involved in transmitting the ranging signal R_g from the NLES 8 to the geostationary satellite 6 is determined and the ranging signal R_g includes position and time data calculated so as, when retransmitted by the geostationary satellite 6, accurately to represent the 15 time of retransmission and the position of the geostationary satellite 6.

The signal retransmitted to the NLES 8 by the geostationary satellite 6 provides a timing loop which 20 allows the delay from the NLES 8 to the geostationary satellite 6 to be determined and also allows ionospheric effects to be measured. In this way, the 25

ranging signal R_g is sufficiently precise to be processed as if it were autonomously generated by the geostationary satellite 6.

5 The satellite radiodetermination system described above may be implemented in stages to provide a progressively enhanced service relative to that provided by the GNSS satellites 2 above, as follows.

10 Stage 1 - Existing or previously planned geostationary communication satellites such as the Inmarsat-3 satellites are used as the geostationary satellites 6 to relay ranging signals and augmentation data R_g, A .

15 Stage 2 - Additional dedicated navigation satellites are put into geostationary orbit as additional geostationary satellites 6. These dedicated navigation satellites are able to generate autonomous ranging signals R_g .

20 Stage 3 - The MEO satellites 10 are launched, providing additional ranging signals R_g and relaying regional augmentation data RA .

25 Stage 1 provides wide area augmentation, for example in accordance with the WAAS specification. Stages 1 to 3 provide more ranging signals, to reduce the reliance on the GNSS satellites 2, which have selective availability.

System Operation Example

Figure 2 shows an example of the satellite radiodetermination system of Figure 1 providing a

navigation service over North and South America. One of the geostationary satellites 6 broadcasts augmentation data A derived by a first regional control station 18a over both North and South America.

5 In a first service area 24a which covers the US, a first service network 20a provides regional augmentation data RAa which is valid only over the first service area 24a, such as more accurate ionospheric data concerning the ionosphere above the

10 US. The regional augmentation data RAa is transmitted to a first satellite access node 14a and broadcast via a first MEO satellite 10a over the first service area 24a. Ranging signals R_g are available in the first service area 24a from GNSS satellites 2a and 2b. The

15 number and identity of the GNSS satellites 2 which are visible above a predetermined minimum elevation angle in the first service area 24a will change with time as these satellites 2 progress in their orbits.

20 A first MEO satellite 10a will also move relative to the first service area 24a until its elevation angle falls below a threshold which is suitable for broadcast reception. The first SAN 14a then selects another MEO satellite 10 having an elevation angle above the threshold for broadcast reception,

25 preferably one that is approaching the first service area 24a. The SAN 14a ceases transmission to the first MEO satellite 10a and begins transmission to the

selected MEO satellite 10 instead. To avoid interruption in broadcast of the regional augmentation data RA, the SAN 14a may transmit to both the first MEO satellite 10a and the selected MEO satellite 10 during handover.

A second service area 24b in South America contains a second regional control station 18b which receives information from a monitoring network which monitors ranging signals received in the second service area 24b. Information from the second regional control station 18b is sent to the first regional control station 18a so that wide area differential correction information is gathered from a monitoring network extending through both North and South America. In this way, the timing and position errors of ranging signals may be determined more accurately. A second service network 20b receives information from the second regional control station 18b and additionally derives more accurate ionospheric information within the area 24b. This information is relayed to a second SAN 14b which transmits the information via a second MEO satellite 10b for broadcast over the second service area 24b.

Hence, augmentation information which is valid over a wide area is broadcast by the geostationary satellite 6, which has a direct line of sight to a wide area. More detailed information of narrower

geographic validity is broadcast by the MEO satellites 10 which are able to cover a smaller area of the earth's surface. In this way, the information broadcast by geostationary and MEO satellites is 5 matched with the coverage areas of these satellites.

Navigation Satellite

Figure 3 shows the navigation payload of one of the MEO satellites 10.

10 The payload includes a frequency standard 30, such as an atomic clock. A highly precise frequency signal f is supplied from the frequency standard 30 to oscillators 32, which provide a time signal t which is referenced to a standard time such as UTC.

15 The time signal t is supplied to a navigation signal generator 34. The payload also includes a telemetry tracking and control (TT&C) interface 42 which receives encrypted TT&C data from a TT&C ground station (not shown). The TT&C interface 42 supplies tracking information to a processor 44 which generates 20 data containing information on the ephemerides of the MEO satellite 10. The ephemerides are written into a memory 46, which applies error correction to avoid data corruption from external radiation and has a double buffer so that previous ephemerides are not 25 immediately overwritten by new ephemerides until the new ephemerides are verified. The ephemerides are read from the memory 46 by the navigation signal

generator 34, which encodes the time signal t and ephemerides using a Gold code of the same family as is used by GPS/Navstar satellites as described in the GPS specification. The Gold code is a pseudo-random noise (PRN) code having low auto-correlation and low cross-correlation with other Gold codes.

Intermediate frequency signals IF containing the encoded ephemerides and time data are supplied to an up-converter 36 which converts the intermediate frequency signal IF to different frequencies F1 and F2 which are respectively transmitted through broadcast antennas 40 and 38.

The frequencies F1 and F2 may be substantially the same as the GPS L1 and L2 frequencies, to maintain compatibility with existing GPS receivers, or they may be offset from the L1 and L2 frequencies so that signals from the MEO satellites 10 may only be received by modified navigation receivers 11. In one embodiment, F1 is 1576 MHz and F2 is 1228 MHz.

The operation of the navigation signal generator 34 is controlled by the processor 44, and status information is supplied by the navigation signal generator 34 to the processor 44.

The payload also includes a feeder link channel interface 48 which receives regional augmentation information RA from the SAN 14. The processor 44 selectively supplies the regional augmentation

information RA to the memory 46 for inclusion in the signal output by the navigation signal generator 34.

The processor 44 is operable in both an autonomous navigation mode and a regional augmentation mode. In the autonomous navigation mode, data supplied by the feeder link channel interface 48 is not sent to the memory 46 and therefore the MEO satellite 10 broadcasts only ranging and status information, at a data rate of 50 bits per second. In the regional augmentation mode, the regional augmentation data RA received from the feeder link channel interface 48 is supplied to the memory 46 for inclusion in the navigation signal. In this mode, the MEO satellite 10 additionally broadcasts information on the integrity and status of the GNSS satellites 2, differential correction information supplied by the service network 20 and alert messages to indicate when satellite radiodetermination may not be possible to a predetermined level of accuracy, at a data rate of 250 bits per second. The processor 44 is switched between these two modes by a command received by the TT&C interface 42. The processor 44 may be switched into autonomous navigation mode when no regional augmentation data is available, for example because no SAN 14 is in view or the SAN 14 is faulty.

Alternatively, the processor 44 may generate dummy data for transmission in the ranging signal R,

the dummy data indicating to the navigation receivers
11 that no regional augmentation data is available.

Satellite Radiodetermination Terminal

Figure 4 shows a simplified block diagram of a
5 navigation receiver 11 for receiving ranging and
augmentation signals in the satellite radio-
determination system described above. The user
terminal 11 includes an antenna 50 for receiving the
ranging signals R_g , R_m and R_n , containing the
10 augmentation information A and the regional
augmentation information RA. A PRN decoder 56 decodes
each ranging signal R and outputs decoded ranging
signals R' and timing data t_s relating to the time of
arrival of each ranging signal. A data decoder 58
15 extracts from the decoded ranging signals data D,
including the augmentation data A, regional
augmentation data RA, the transmission time t of each
ranging signal and the ephemerides of the satellites.
A radiodetermination section 54 receives the data D
20 and timing data t_s , calculates therefrom the values of
ionospheric delays incurred by the dual frequency
ranging signals R_m and the approximate position of the
navigation receiver 11 and outputs this data to an
ionospheric modelling section 60, together with
25 ionospheric data included in the regional augmentation
data RA and the augmentation data A.

From this data, the ionospheric modelling section

60 calculates ionospheric pierce points at which each of the ranging signals R passed through the ionosphere and estimates the ionospheric delay thereby incurred by single-frequency ranging signals R, such as the L1 GPS signals, for which the ionospheric delay cannot be measured directly. The ionospheric modelling section 60 outputs an estimated ionospheric delay for each of the single frequency ranging signals R together with error bounds for the estimated delay.

10 The radiodetermination section 54 receives the estimated ionospheric delays and subtracts them from the time of arrival t_s of the single-frequency signals. The directly measured delays incurred by the dual frequency ranging signals are subtracted from the times of arrival t_s of these signals. The augmentation data A and regional augmentation data RA include information on errors in the ranging signals, which is used to correct the position and time information in each of the ranging signals. The augmentation data A and regional augmentation data RA also include integrity information which indicates whether any of the satellites has failed or is operating incorrectly; the ranging signals R from such satellites are not used for radiodetermination.

15

20

25 The radiodetermination section 54 then calculates an accurate position P and time T from the corrected ranging signals R and an estimate of the error in the

position P and time T from the error bounds in ionospheric delay indicated by the ionospheric modelling section 60 and from error bounds for the ranging signals indicated by the augmentation data 5 RA,A. If the likely error in the position P and time T exceeds a predetermined value, the radiodetermination section 54 may indicate a visual or audible warning, so that users know that the output should not be relied upon for certain applications.

10 An explanation of the operation of the ionospheric modelling section 60 will now be given with reference to Figures 5 and 6.

15 The augmentation data A broadcast by the geostationary satellites 6 and the regional augmentation data RA broadcast by MEO satellites 10 includes ionospheric data comprising a set of values for calculating ionospheric delay for points on a grid G mapped onto the earth's surface. The grid is centred on the nadir N of a geostationary satellite 20 position and the ionospheric delay value at each grid point g_i represents the vertical ionospheric delay at that grid point.

25 Information is seldom available for all the grid points g_i and the ionospheric data therefore comprise a list of addresses i of grid points g_i for which ionospheric data is available, together with the associated vertical ionospheric delay and delay error

for each of these points. The ionospheric data also includes the position of the nadir N on which the grid of points is centred.

The format for ionospheric data described above 5 is designed for broadcast from a geostationary satellite, but is also used for ionospheric information broadcast by the MEO satellites 10. The SAN 14 calculates a hypothetical geostationary position so that the coverage area of the MEO 10 satellite 10, within which the satellite is visible above 5° elevation, falls within the grid of points g, based on that position. Ionospheric data is broadcast for some or all of the grid points which fall within the coverage area of the MEO satellite 10. Thus, the 15 ionospheric data broadcast by the geostationary satellite 6 and the MEO satellites 10 have compatible formats.

In order to estimate accurately the ionospheric delay for each ranging signal R, the ionospheric 20 modelling section 60 of the navigation receiver 11 must calculate a pierce point at which the ranging signal R passes through the ionosphere on its way to the user and apply the appropriate ionospheric delay value for that pierce point.

25 As shown in Figure 6, a ranging signal R is transmitted by a satellite, such as one of the MEO satellites 10, at an elevation angle ϵ with respect to

the navigation receiver 11. The ranging signal R passes the level of maximum electron density I_0 of the ionosphere at the pierce point PP . The height H of the level I_0 is assumed to be 400km above the earth's surface. The navigation receiver 11 is able to derive its approximate position from the uncorrected ranging signal R , which also contains information on the position of the satellite 10. From this information, and from the radius r of the earth, the latitude and 10 longitude of the pierce point PP is calculated in a known manner.

The calculated pierce point PP does not usually coincide with one of the grid points g_i for which ionospheric information is available. The value for 15 ionospheric delay must therefore be inter-polated between grid points g_i, g_{i+1} for which ionospheric information is available. The ionospheric modelling section 60 generates a modelling function which may be varied by one or more parameters so as to fit the 20 ionospheric information at the surrounding grid points g_i and which is used to interpolate the ionospheric delay value at the pierce point PP .

A suitable model for interpolating ionospheric delay values has been specified for the WAAS. In this 25 model, the ionospheric delay values for the four grid points at the corners of a cell containing the pierce point PP are used to interpolate an ionospheric delay

value at the pierce point by means of a weighting function which provides a continuous surface as a function of longitude and latitude. Alternatively, a linear interpolation may be taken between pairs of 5 grid points in both the longitudinal and latitudinal directions.

In addition, the ionospheric delay modelling section 60 may fit the modelling function to the directly measured ionospheric delay values obtained 10 from the dual frequency ranging signals R_m , by calculating the pierce points PP for these signals and adjusting the parameters of the modelling function to fit the measured ionospheric delay values for these pierce points PP.

15 The modelling function need not fit the ionospheric information and measured delay values exactly; instead, an approximate fit such as a least squares fit may be calculated.

The vertical ionospheric delay value at the 20 pierce point is thereby calculated. However, the ranging signal R travels a distance l through the ionosphere which is greater than the vertical height h of the ionosphere, as a result of the slant angle α which the path of the ranging signal R makes with 25 the vertical. The vertical ionospheric delay value is therefore multiplied by an obliquity factor, to take into account the greater length of ionosphere

traversed.

User Operation Example

A specific example will now be described of the
operation of an alternative embodiment of a satellite
5 radiodetermination system which provides a navigation
service for Africa in which a geostationary satellite
6 provides a ranging signal R_g and augmentation
information A comprising correction messages for the
GNSS satellite ranging signals R_n , but ionospheric
10 correction information is not provided through the
geostationary satellites 6 in this embodiment, since
insufficient information is available for Africa as a
whole.

However, regional monitoring stations are
15 provided by local service providers in Kenya. The
monitoring stations monitor the ranging signals from
the MEO satellites 10 and the GNSS satellites 2 and
additionally receive the augmentation information A
broadcast by the geostationary satellites 6. From
20 this information a vertical ionospheric delay value
and ionospheric delay error bounds are estimated which
are applicable for all users in Kenyan territory and
airspace. This information is relayed to a SAN 14 for
broadcast through an MEO satellite 10 which covers
25 Kenya at that time.

The navigation satellites visible by a navigation
receiver 11 approaching Nairobi are, for example,

those shown in Table 1 below.

TABLE 1

| | <u>Satellite</u> | <u>Azimuth</u> | <u>Elevation</u> |
|----|------------------|----------------|------------------|
| 5 | MEO 2 | 184 | 27 |
| | MEO 9 | 310 | 12 |
| | MEO 10 | 40 | 11.5 |
| | AOR-E GEO | 269 | 30 |
| | IOR GEO | 91 | 58 |
| | GPS 2 | 250 | 73 |
| | GPS 4 | 355 | 24 |
| 10 | GPS 13 | 150 | 27 |

The satellite AOR-E is an Inmarsat (TM) satellite serving the eastern Atlantic Ocean region, while the satellite IOR serves the Indian Ocean region.

15 The navigation receiver is able to determine the approximate positions of all the above satellites from ranging signals generated or relayed by the satellites, without ionospheric correction. Estimates of the ionospheric delay in the ranging signals from each of the satellites are then obtained as follows.

20 The ionospheric delay is calculated directly for the dual frequency ranging signals transmitted by the satellites MEO₁, MEO₂ and MEO₃. The AOR-E geostationary satellite is identified as being in the same quadrant as the MEO₁ satellite. The ionospheric

delay value in the MEO, ranging signal is used to estimate the ionospheric delay in the AOR-E GEO ranging signal, by compensating for the difference in elevation angles between the MEO, satellite and the 5 AOR-E geostationary satellite. The ionospheric delays for the GPS, and GPS₁, satellites are estimated in the same way, using the ionospheric delay value measured for the MEO,.

10 The GPS₂ satellite is approximately overhead and therefore the ionospheric delay information provided by the Kenyan monitoring stations is used, with a small obliquity factor correction for the difference between the actual elevation angle of 72° and 90°. The ionospheric delay error bound data are applied to 15 each of the estimated ionospheric delays which are not measured directly from a dual frequency ranging signal.

11 In this example, the navigation terminal receives ranging signals from eight different 20 satellites and is able to calculate or estimate the ionospheric delay for each ranging signal without ionospheric data being provided in the augmentation data A. In addition, integrity information received 25 from the geostationary satellites is used to determine whether any of the ranging signals should not be used for satellite radiodetermination. Thus, the result of the radiodetermination is accurate and reliable.

Regional Augmentation Information

In the above example, ionospheric delay information relevant to Kenya is relayed through one or more of the MEO satellites 10. Each MEO satellite 5 is able to broadcast over an area much wider than Kenya, for example, and the SAN 14 receives both the data provided by the Kenyan service provider and data provided by other networks. In the transmission from the SAN 14, the data from each network is assigned a different time slot in a repeating time frame, so that 10 the information from the different monitoring networks is time division multiplexed. Table 2 below shows an example of the allocation of time slots to each of the satellites MEO₂, MEO, and MEO₁₀ in the above example.

15 TABLE 2

| Satellite | Slot 1 | Slot 2 | Slot 3 | Slot 4 | Slot 5 | Slot 6 |
|-----------|--------|--------|--------|--------|--------|--------|
| MEC 2 | Kenya | Africa | Other | Other | Africa | Other |
| MEC 9 | Kenya | Other | Europe | Other | Other | Europe |
| MEC 10 | Kenya | Other | Other | Other | Other | Other |

20 The satellite MEO₂ transmits, in slots 2 and 5, regional augmentation data which is valid over the whole of Africa and this information may additionally be used by the navigation receiver 11 in Kenya.

Each slot may for example be a 1 second slot in

a 6 second time frame and carry 250 data bits.

Slots may be allocated by the SAN 14 to service providers during a period in which the nadir of the MEO satellite 10 carrying the regional augmentation information passes over a predetermined region, allocated to the service provider, defined for example by longitude and latitude boundaries. For example, each region may comprise a 5° longitudinal strip of the Northern or Southern Hemisphere.

10 Each slot may be shared by several service providers, which individually do not supply enough data to occupy a whole slot, so that the full capacity of each slot is used. The data from each service provider within the slot is identified by a code allocated to that service provider. More than one slot may be allocated to service providers which require more capacity than can be provided by one slot. Charging data for calculating a charge to the service provider is generated according to the duration for which capacity on the MEO satellite 10 is allocated to the service provider and according to the proportion of the capacity used during that time.

20 Alternatively, slots may be allocated to service providers during a period in which the MEO satellite 10 is visible above a minimum elevation angle, such as 5°, from the service area for which the service provider provides regional augmentation data RA.

The regional augmentation data in each time slot is preferably encrypted to ensure that it can only be decoded by licensed navigation receivers 11. All licensed receivers may use the same algorithms for 5 performing radiodetermination using the ionospheric delay data, so that radiodetermination is performed to a common standard.

Additionally, users may be required to purchase a smart card for insertion in the navigation receiver 10 11 to allow access to some or all of the regional augmentation information RA broadcast by the MEO satellites. In this way, revenue may be collected by the service providers. Alternatively, the user terminals may have a keyboard for entering a code 15 which enables access to one or more of the regional augmentation information slots.

In this way, different types of information may be made available to different users, depending on the area for which they need ionospheric information or 20 the level of accuracy which they require, and the users may only be charged for the information which they need.

In the above example, the different types of augmentation information are time division 25 multiplexed. However, the different information channels may be multiplexed together in other ways well known in the art, such as by code division

multiplexing or frequency division multiplexing.

The information in each regional augmentation information channel may include data, such as country codes, for identifying the area for which the ionospheric data is valid, data indicating the reliability of ionospheric data and data indicating for what period the ionospheric data is valid.

Since the ionospheric delay modelling section 60 of the navigation receiver 11 is able to combine ionospheric delay information with direct ionospheric delay measurements, a more accurate model of the ionosphere is used to compensate for ionospheric delay. Furthermore, regional augmentation data RA is received which is relevant to the local area in which the navigation terminal 11 is located. Integrity data and error bound data is received both in the regional augmentation data RA and the augmentation data A. In this way, highly accurate position readings P and time readings T may be calculated, together with estimates of the level of accuracy of these readings and warnings if the level of accuracy falls below a predetermined threshold.

Such accurate and reliable radiodetermination greatly extends the potential applications of satellite radiodetermination.

For example, the above described satellite radio-determination system may be used where safety is

critical, such as landing aircraft in low visibility conditions. The system also has maritime applications in that it provides sufficient accuracy for harbour approaches in restricted visibility, and may also find 5 applications in train control where sufficient accuracy is needed to determine on which track a train is running. The system may provide accurate time readings for use by laboratories or communication systems which require precise synchronisation.

10 Since all of the ranging and augmentation information is provided by satellite, the need to install terrestrial differential correction systems may be overcome.

15 Although the above embodiments use MEO satellites such as I-CO (TM) satellites, other satellite constellations could be used such as those proposed for the ODYSSEY (TM), IRIDIUM (TM), GLOBALSTAR (TM) and TELEDESIC (TM) satellite communications systems. Satellites in low earth orbits (LEO) produce greater 20 Doppler shift in their signals, but this may be overcome by appropriate compensation in the receivers. The satellite configurations described in the embodiments are particularly advantageous, but alternative configurations may be used. For example, 25 autonomous navigation signal generation equipment may be replaced by transponders for retransmitting navigation signals in the non-geostationary

satellites. Regional augmentation data may be broadcast by geostationary or non-geostationary satellites having multiple spot beams, with the regional validity of the data broadcast in each spot beam being matched to the coverage area of each that spot beam.

5 Navigation receivers may determine their altitude from map data giving altitude as a function of longitude and latitude, or from barometric pressure, 10 so that only three ranging signals are required to determine longitude, latitude and time.

CLAIMS:

1. Satellite radiodetermination apparatus, comprising:

5 a radio receiver for receiving a multiple frequency ranging signal from a first satellite and a further ranging signal from a second satellite;

10 deriving means for deriving first ionospheric delay data from said multiple frequency ranging signal; and

15 estimating means for estimating second ionospheric delay data for the further ranging signal on the basis of said first ionospheric delay data.

20 2. Apparatus as claimed in claim 1, further comprising data receiving means for receiving ionospheric data, said estimating means being operable to estimate the second ionospheric delay data additionally on the basis of said ionospheric data.

25 3. Apparatus as claimed in claim 2, wherein said data receiving means is arranged to receive said ionospheric data from a satellite.

4. Apparatus as claimed in claim 2 or 3, wherein said ionospheric data represents a plurality of ionospheric delay values corresponding to a plurality of spatially separated points.

25 5. Apparatus as claimed in any preceding claim, wherein said estimating means includes modelling means for generating a model of spatial variation of

ionospheric delay on the basis of said first ionospheric delay data, said estimating means being operable to estimate said second ionospheric delay data on the basis of said model.

5 6. Apparatus as claimed in claim 5 when dependent on claim 2, wherein said modelling means is operable to generate said model on the basis of said ionospheric data.

10 7. Apparatus as claimed in claim 5 or claim 6, wherein said model comprises a function which is variable in accordance with one or more parameters, said modelling means being arranged to calculate said one or more parameters such that said function is fitted to said first ionospheric delay data.

15 8. Apparatus as claimed in claim 7 when dependent on claim 6, wherein said modelling means is arranged to calculate said one or more parameters such that said function is additionally fitted to said ionospheric data.

20 9. A method of satellite radiodetermination, comprising receiving a multiple frequency ranging signal from a first satellite;

receiving a further ranging signal from a second satellite, deriving first ionospheric delay data from said multiple frequency ranging signal; and

25 estimating second ionospheric delay data for the further ranging signal on the basis of said first

ionospheric delay data.

10. A satellite payload adapted for a satellite designed for a non-geostationary orbit, comprising:

5 a clock for generating a time signal;

a ranging signal generator for generating a ranging signal including timing data derived from said time signal;

15 relaying means for retransmitting data received by the satellite from a ground station; and

means for selectively activating and deactivating said relaying means independently of the activation of the ranging signal generator.

11. A satellite payload adapted for a satellite designed for a non-geostationary orbit, comprising:

15 a clock for generating a time signal;

a ranging signal generator for generating a ranging signal including timing data derived from said time signal;

20 relaying means for retransmitting received data received by the satellite from a ground station;

means for detecting an absence of said received data; and

means for generating dummy data for transmission in response to detection of said absence.

25 12. Satellite radiodetermination apparatus, comprising:

means for receiving a plurality of ranging

signals from a plurality of satellites;

5 augmentation signal receiving means for receiving augmentation signals including identifying data and a plurality of sets of augmentation data, said identifying data indicating the origin of said sets of augmentation data; and

10 selecting means for selecting one or more of said sets of augmentation data on the basis of -said identifying data, said apparatus being arranged to perform radiodetermination on the basis of said plurality of ranging signals corrected in accordance with said selected one or more sets of augmentation data.

15 13. Apparatus as claimed in claim 12, wherein said sets of augmentation data include a first set of data relating to corrections to said ranging signals and a second set of data relating to corrections to said first set of data, said apparatus being arranged to correct said first set of data on the basis of said 20 second set of data.

14. A method of satellite radiodetermination, comprising:

receiving a plurality of ranging signals from a plurality of satellites;

25 receiving augmentation signals including identifying data and a plurality of sets of augmentation data, said identifying data indicating

the origins of said sets of augmentation data;

selecting one or more of said sets of augmentation data on the basis of said identifying data; and

5 performing radiodetermination on the basis of said selected one or more sets of augmentation data.

15. Apparatus for providing augmentation data for transmission by a satellite, comprising:

means for receiving the augmentation data;

10 means for providing position data relating to the position of the satellite;

determining means for determining whether the position data satisfies a predetermined criterion; and

15 means for selectively enabling output of said augmentation data for transmission to said satellite in response to the determining means.

16. A method of providing augmentation data for transmission by a satellite, comprising:

20 providing position data relating to the position of the satellite;

determining whether the position data satisfies a predetermined criterion; and

25 selectively enabling output of said augmentation data for transmission to a satellite in response to the result of said determining step.

17. Satellite radiodetermination apparatus, comprising:

means for receiving a plurality of ranging signals from a corresponding plurality of satellites; and

5 means for receiving ionospheric delay data, the apparatus being arranged to perform radiodetermination on the basis of said plurality of ranging signals and selectively on the basis of said ionospheric delay data in response to authorization data provided at said apparatus.

10 18. Apparatus as claimed in claim 17, further including means for receiving differential correction data which is substantially independent of ionospheric delay, wherein said apparatus is arranged to perform radiodetermination additionally on the basis of said differential correction data.

15 19. Apparatus as claimed in claim 17 or claim 18, wherein said ionospheric delay data is encrypted, and said apparatus includes decryption means for decrypting said ionospheric delay data in response to said authorization data.

20 20. Apparatus as claimed in any one of claims 17 to 19, including input means for inputting said authorization data.

25 21. Apparatus for providing augmentation data for transmission via a satellite, comprising:

means for receiving said augmentation data which includes unencrypted ionospheric delay data and

unencrypted differential correction data which is substantially independent of ionospheric delay;

means for encrypting said ionospheric delay data;

and

5 means for outputting said encrypted ionospheric delay data and said unencrypted differential correction data for transmission via said satellite.

22. A method of providing ionospheric delay data and differential correction data which is substantially independent of ionospheric delay for 10 transmission via a satellite, comprising:

receiving said ionospheric delay data and said differential correction data in an unencrypted form;

encrypting said ionospheric delay data; and

15 outputting said encrypted ionospheric delay data and said unencrypted differential correction data for transmission via said satellite.

23. Satellite radiodetermination apparatus, comprising:

20 means for receiving a plurality of ranging signals from a corresponding plurality of satellites;

means for receiving ionospheric delay data; and

means for receiving residual error data relating 25 to residual errors in said ionospheric delay data, said satellite radiodetermination apparatus being arranged to perform radiodetermination on the basis of said plurality of ranging signals, said ionospheric

delay data and said residual error data.

24. Apparatus as claimed in claim 23, wherein
said residual error information includes error bound
information relating to the error bounds of said
5 ionospheric delay information.

25. Apparatus for determining residual errors in
a satellite radiodetermination system, comprising:

means for receiving a plurality of ranging
signals from a plurality of satellites;

10 means for receiving ionospheric delay data and
differential correction data relating to errors in
said ranging signals which are independent of
ionospheric delay;

15 calculating means for calculating a position or
time on the basis of said ranging signals corrected on
the basis of said differential correction data and
said ionospheric delay data; and

20 error calculating means for calculating errors in
said ionospheric delay data on the basis of the
difference between said calculated position or time
and a predetermined reference position or time.

25 26. Apparatus as claimed in claim 25, wherein
said means for receiving said ranging signals
comprises a dispersed plurality of receiving stations,
said calculating means being arranged to calculate a
plurality of positions corresponding respectively to
said receiving stations, and said error calculating

means being arranged to calculate said errors on the basis of the respective differences between said calculated positions and predetermined positions corresponding to said receiving stations.

5 27. A satellite radiodetermination receiver including apparatus as claimed in any one of claims 1 to 8, 12, 13, 17 to 20, 23 and 24.

28. A terrestrial station including apparatus as claimed in any one of claims 15, 16, 21 or 26.

10 29. A satellite including a satellite payload as claimed in claim 10 or 11.

30. A satellite radiodetermination system including a plurality of satellite radiodetermination receivers as claimed in claim 27 and at least one 15 terrestrial station as claimed in claim 28.

31. A satellite radiodetermination apparatus substantially as herein described with reference to Figures 4 to 6 of the accompanying drawings.

32. Apparatus substantially as herein described 20 with reference to Figures 1 and 2 of the accompanying drawings.

33. A satellite payload substantially as herein described with reference to Figure 3 of the accompanying drawings.



The
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Claims searched: 1 to 9

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Databases searched:

UK Patent Office collections, including GB, EP, WO & US patent specifications, in:

UK CI (Ed.O): H4D(DPBC)

Int CI (Ed.6): G01S

Other:

Documents considered to be relevant:

| Category | Identity of document and relevant passage | Relevant to claims |
|----------|---|--------------------|
| A | EP0609935A MAGNAVOX ELECTRONIC SYSTEMS | |

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